

1/16 DIN controller

- Programmable open or closed loop servomotor control.
- Control output programmable as 3-wire servomotor or time proportional output.
- 2 logic inputs used for the selection of:
 - operative set point,
 - AUTO/MANUAL mode.
- AUTO/MANUAL transfer with programmable valve positioning.
- SMART function (Auto-tuning algorithm).
- ECP software package further simplifies the instrument configuration.
- SDDE driver, it is a simple object oriented interface between ERO instruments and Windows'® applications on PC.

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LFS Servo

Distribué par :



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LFS - Servo







GENERAL SPECIFICATIONS

Case: P

Polycarbonate - Self extinguishing degree according to UL 746 C designed and tested for IP 65 (*) and NEMA 4X (*) for indoor locations

(when panel gasket is installed).

(*) Test performed in accordance with IEC 529, CEI 70-1 and NEMA 250-

1991 STD.

Dimensions: (according to DIN 43700) 48 x 48 mm - Depth 122 mm

Weight: 250 g max.

Power supply (switching mode): from 100 to 240 V AC. 50/60 Hz (+10 % to -15 % of the nominal value)

Power consumption: 5.5 W max.

Insulation: a double or reinforced insulation is guaranteed between the power

supply input and all the instrument inputs and outputs.

Common mode rejection ratio:

Normal mode rejection ratio:

Electromagnetic compatibility and safety requirements: This instrument is marked CE.

Therefore, it is conforming to council directives 89/336/EEC (reference harmonized standard EN 50081-2 and EN 50082-2) and to council directives 73/23/EEC and 93/68/EEC (reference harmonized

standard EN 61010-1).

> 120 dB @ 50/60 Hz.

> 60 dB @ 50/60 Hz.

Installation category:

Sampling time: - 250 ms for linear inputs

- 500 ms for TC inputs

Accuracy: \pm 0.2% f.s.v. @ 25 °C (77 °F) and nominal power supply voltage. emperature: from 0 to +50 °C (32 to 122 °F).

Operative temperature: Storage temperature: from

-20 to +70 °C (-4 to 158 °F).

Humidity: from 20% to 85 % RH not condensing

INPUT

Thermocouple

Burn out:

Detection of the open input circuit (wires or sensor) with underrange or overrange selectable indication.

Cold junction:

automatic compensation for an ambient temperature between 0 and 50 $^{\circ}\text{C}.$

Cold junction compensation error: 0.1 °C/°C

 $> 1M\Omega$.

Input impedance: Calibration:

according to IEC 584-1.

STANDARD RANGE TABLE

TC tipo	°C	Scale	°F	
L	-100 / 900		-150 / 1650	
L	-100.0 / 900.0			
J	-100 / 1000		-150 / 1830	
J	-100.0 / 999.9			
K	-100 / 1370		-150 / 2500	
K	-100.0 / 999.9			
N	-100 / 1400		-150 / 2550	
R	-50 / 1760		-60 / 3200	
S	-50 / 1760		-60 / 3200	
Т	-200 / 400		-330 / 750	
Т	-199.9 / 400.0			



Linear input (mA and V)

Read-out: Decimal point: keyboard programmable from -1999 to 4000.

programmable in any position.

STANDARD RANGE TABLE

Input		Impedar	ice
0 - 20	mA	< 5	Ω
4 - 20	mΑ	< 5	Ω
0 - 60	mV	> 1	$M\Omega$
12 - 60	mV	> 1	$M\Omega$
0 - 5	V	> 400	kΩ
1 - 5	V	> 400	kΩ
0 - 10	V	> 400	kΩ
2 - 10	V	> 400	kΩ

LOGIC INPUTS

The LFS-Servo is equipped with 2 logic inputs (contact closure).

The first is used for the operative set point selection SP, SP2.

The second is used for AUTO/MANUAL mode selection.

CONTROL OUTPUT

A) Closed loop servomotor output.

Feedback potentiometer range: from 100 Ω up to 1K Ω .

The initial and final stroke points are keyboard programmable. **band:** from 1 % to 50 % of the selected feedback potentiometer span.

Servomotor dead band: from 1 % to 50 % of the selected direct or reverse programmable.

Valve position limiter: low and high limiters programmable.

B) Open loop servomotor output with valve position indication.

Indication potentiometer range: from 100Ω up to $1K\Omega$.

The initial and final stroke points are keyboard programmable.

Servomotor dead band: from 1 % to 50 % of the selected servomotor stroke time.

Servomotor stroke time: programmable from 25 seconds to 3 minutes.

Control action: direct or reverse programmable.

C) Open loop servomotor output without valve position indication.

Servomotor dead band: from 1 % to 50 % of the selected servomotor stroke time.

Servomotor stroke time: from 25 seconds to 3 minutes. **Control action:** direct or reverse programmable.

D) One time proportioning output.

Output used: output 1

Control action: direct or reverse programmable.

Output cycle time: from 1 second to 200 seconds.

Output power limiting: high limit programmable.

E) Two time proportioning outputs.

Output used: output 1 and 3

Output cycle time: from 1 second to 200 seconds.

Output power limiting: high limit programmable.

CONTROL ACTION

Algorithm: PID + SMART

Types: - one control output (heating)

- two control outputs (heating and cooling)

Proportional Band: programmable from 1.0 % to 200.0% of the input span. Setting a PB equal to 0 the control action becomes ON/OFF.

Hysteresis (for ON/OFF control action): from 0.1% to 10.0 % of the input span.

Integral time: from 1 second to 20 minutes.

Derivative time: from 1 second to 10 minutes or excluded.

Integral preload: - for one control output, from 0 to 100% of the output range.

- for two control outputs, from -100 % to +100 % of the heating/

cooling output range.

AUTO/MANUAL mode: selectable by front pushbutton or logic input. **Relative cooling gain:** from 0.20 to 1.00 referred to the proportional band.

Overlap / dead band: from - 20 % (dead band) to + 50 % (overlap) of the proportional

band.

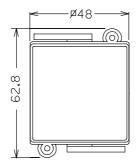
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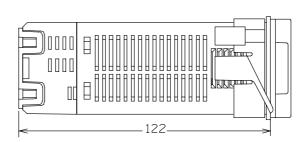
OUTPUTS		
Out 1 and 2	Function:	- Servo-motor output
	Relay type:	 One time proportional output. two interlocked SPST relayes.
	Contact rating:	3 A @ 250 Vac on resistive load
Out 3	Function:	- Time proportional output.
	Relay type:	- Alarm 1 output SPST relay.
	Contact rating:	2 A @ 250 Vac on resistive load
Out 4	Function:	- Alarm 2 and/or alarm 3 output
	Relay type: Contact rating:	SPST relay. 2 A @ 250 Vac on resistive load
	Contact rating.	Z A @ 200 vac on resistive load
ALARMS		
	Alarm functions:	each alarm can be configured as process alarm, band alarm or deviation alarm.
	Alarm reset:	automatic or manual reset programmable on each alarm.
	Mask Alarm:	programmable on each alarm.
Process alarm:	Operative mode:	high or low programmable.
	Threshold: Hysteresis:	programmable in engineering unit within the entire range. programmable from 0.1 % to 10.0 % of the input span.
_	nysteresis.	programmable from 0.1 % to 10.0 % of the input span.
Band alarm:	Operative mode: Threshold:	inside or outside band programmable. programmable from 0 to 500 units.
	Hysteresis:	programmable from 0.1 % to 10.0 % of the input span.
Deviation alarm:	Operative mode	high or low programmable
Deviation alarm.	Operative mode: Threshold:	high or low programmable. programmable from -500 to +500 units.
	Hysteresis:	programmable from 0.1 % to 10.0 % of the input span.
SET POINTS		
Set points:		2 set point are available (SP and SP2) transfer may be driven
	Set point limiters:	by logic input (contact closure). set point low limit and set point high limit are programmable.
SERIAL INTERFACE		
	Type:	Isolated RS 485
	Protocol type: Baud rate:	MODBUS, JBUS, ERO polling/selecting. programmable from 600 to 19200 BAUD.
	Byte format:	7 or 8 bit programmable.
	Parity: Stop bit:	even, odd or none programmable.
	Address:	one from 1 to 95 for ERO protocol.
		- from 1 to 255 for all the other protocols.
	Output voltage levels:	according to EIA standard.

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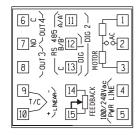


DIMENSIONS

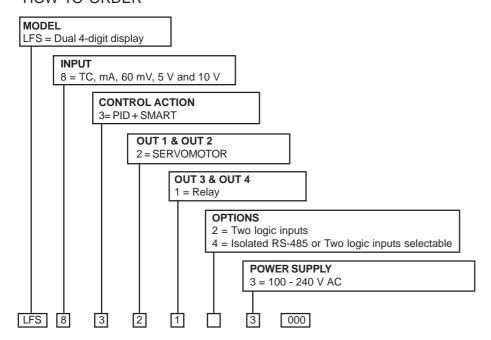




REAR TERMINAL BLOCK



HOW TO ORDER





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